

# Optimized CS-Wave imaging with tailored data-sampling and efficient reconstruction

B Bilgic, H Ye, LL Wald, K Setsompop

Martinos Center for Biomedical Imaging, Charlestown, MA, USA Department of Radiology, Harvard Medical School, Boston, MA, USA



# Declaration of Financial Interests or Relationships

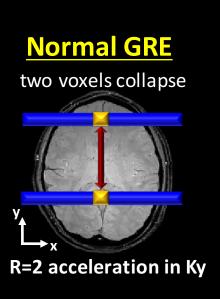
Speaker Name: Berkin Bilgic

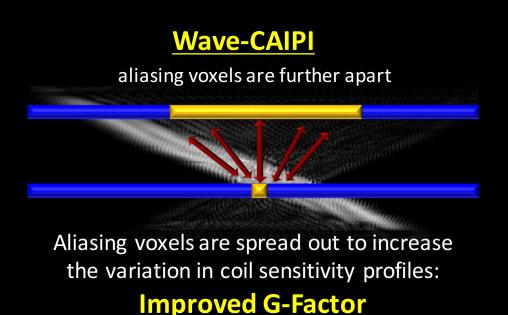
I have no financial interests or relationships to disclose with regard to the subject matter of this presentation.

# Wave-CAIPI for 3D-GRE

- Wave-CAIPI modifies 3D GRE trajectory to follow a corkscrew along each readout line [1]
- For accelerated acquisitions, this spreads the aliasing in all 3D dimensions to substantially improve parallel imaging
- Acquisition has the same off-resonance characteristic as Normal GRE (voxel shift in readout), and recon is fully Cartesian

# Wave-CAIPI trajectory KZ KX KX KY





# **Compressed Sensing Wave**

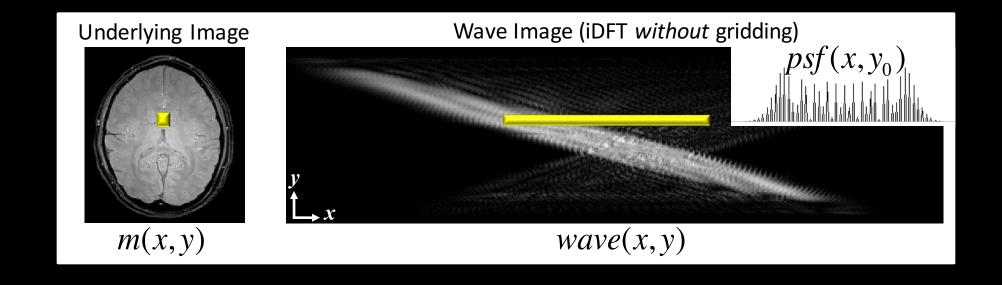
- Recently introduced CS-Wave [1] employed Poisson sampling and Wavelet penalty to combine Compressed Sensing with Wave encoding
- We propose optimized CS-Wave with
  - Efficient ADMM reconstruction
  - Total Variation regularization
  - Tailored data-sampling
- When combined, these double the improvement achieved by the previous CS-Wave
- Providing 20% RMSE reduction over Wave-CAIPI at 15-fold accl

# Compressed Sensing Wave

- Recently introduced CS-Wave [1] employed Poisson sampling and Wavelet penalty to combine Compressed Sensing with Wave encoding
- We propose optimized CS-Wave with
  - Efficient ADMM reconstruction
  - Total Variation regularization
  - Tailored data-sampling
- Combining CS-Wave with Simultaneous MultiSlice (SMS) Echo-Shift strategy [2] further increases the acceleration to 30-fold (15×2)
- Enabling Quantitative Susceptibility Mapping (QSM) from 3 head orientations at long TE and 1.5 mm iso in 72 sec (24 sec / orientation)

Despite following a non-Cartesian trajectory, Wave encoding can be expressed in Cartesian space through point spread function (psf):

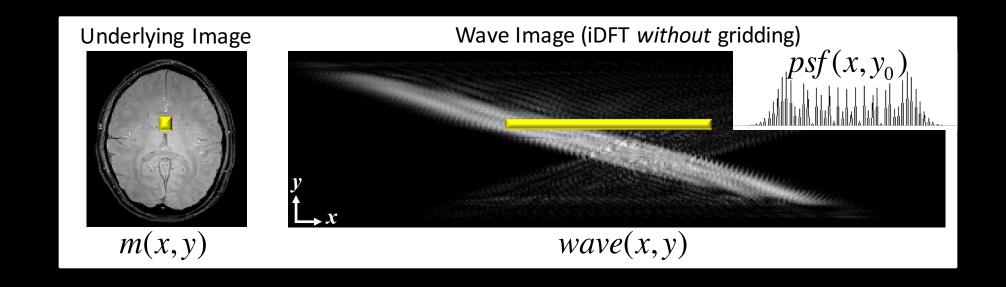
$$wave(x, y) = psf(x, y) \otimes m(x, y)$$



Despite following a non-Cartesian trajectory, Wave encoding can be expressed in Cartesian space through point spread function (psf):

$$wave(x, y) = F_x^H \cdot Psf(k_x, y) \cdot F_x \cdot m(x, y)$$

No need for gridding, simple DFT



Extend to 3D using both  $G_v$  and  $G_z$  sinusoidal gradient waveforms:

$$wave(x, y, z) = F_x^H \cdot Psf(k_x, y, z) \cdot F_x \cdot m(x, y, z)$$

And go to 3D k-space by applying DFT to both sides:

$$\underline{\mathbf{F}_{\mathrm{xyz}}} \cdot wave(x, y, z) = \underline{\mathbf{F}_{\mathrm{yz}}} \cdot \mathrm{Psf}(k_{x}, y, z) \cdot \mathbf{F}_{\mathrm{x}} \cdot m(x, y, z)$$

And go to 3D k-space by applying DFT to both sides:

$$\underline{k} = F_{yz} \cdot Psf \cdot F_{x} \cdot m$$

Include coil sensitivities and undersampling mask to obtain the forward SENSE model

$$k = \underline{\mathbf{M}} \cdot \mathbf{F}_{yz} \cdot \mathbf{Psf} \cdot \mathbf{F}_{x} \cdot \underline{\mathbf{S}} \cdot m$$

Include coil sensitivities and undersampling mask to obtain the forward SENSE model

$$k = M \cdot \underline{E} \cdot m$$
encoding  $E = F_{yz} \cdot Psf \cdot F_{x} \cdot S$ 

Regularized least squares to incorporate Compressed Sensing:

$$1/2||k-\mathbf{M}\cdot\mathbf{E}\cdot\boldsymbol{m}||_{2}^{2} + \lambda||\mathbf{R}\cdot\boldsymbol{m}||_{1}$$

• For efficient optimization, we adopt ADMM [1,2] and introduce auxiliary variables for data consistency and regularization terms:

$$1/2||k - \mathbf{M} \cdot \mathbf{E} \cdot m||_{2}^{2} + \lambda ||\mathbf{R} \cdot m||_{1}$$

$$c = \mathbf{E} \cdot m \qquad r = \mathbf{R} \cdot m$$

This allows us to separate the difficult 3D optimization problem into smaller subproblems that are solved in closed form for  $\mathcal C$  and  $\mathcal Y$ 

• For efficient optimization, we adopt ADMM [1,2] and introduce auxiliary variables for data consistency and regularization terms:

$$1/2||k - \mathbf{M} \cdot \mathbf{E} \cdot m||_{2}^{2} + \lambda ||\mathbf{R} \cdot m||_{1}$$

$$c = \mathbf{E} \cdot m \qquad r = \mathbf{R} \cdot m$$

And the image update is found by a simple linear combination of data consistency and regularization

$$(\alpha \cdot S^{2} + \beta \cdot R^{2}) \cdot m = \alpha \cdot E^{H}(c - d_{c}) + \beta \cdot R^{H}(r - d_{r})$$

$$d_{c} \& d_{r}: \text{ dual variables}$$

$$\alpha \& \beta: \text{ Lagrange parameters}$$

• For efficient optimization, we adopt ADMM [1,2] and introduce auxiliary variables for data consistency and regularization terms:

$$1/2 ||k - \mathbf{M} \cdot \mathbf{E} \cdot m||_{2}^{2} + \lambda ||\mathbf{R} \cdot m||_{1}$$

$$c = \mathbf{E} \cdot m \qquad r = \mathbf{R} \cdot m$$

And the image update is found by a simple linear combination of data consistency and regularization: closed-form for Wavelet

$$(\alpha \cdot S^{2} + \beta \cdot R^{2}) \cdot m = \alpha \cdot E^{H}(c - d_{c}) + \beta \cdot R^{H}(r - d_{r})$$

$$R^{2} = I \text{ for Wavelet}$$

$$S^{2} = SoS \text{ of sensitivities}$$

• For efficient optimization, we adopt ADMM [1,2] and introduce auxiliary variables for data consistency and regularization terms:

$$1/2||k - \mathbf{M} \cdot \mathbf{E} \cdot m||_{2}^{2} + \lambda ||\mathbf{R} \cdot m||_{1}$$

$$c = \mathbf{E} \cdot m \qquad r = \mathbf{R} \cdot m$$

And the image update is found by a simple linear combination of data consistency and regularization: closed-form for Wavelet

$$m = (\alpha \cdot S^2 + \beta \cdot I)^{-1} \cdot \left[\alpha \cdot E^H(c - d_c) + \beta \cdot R^H(r - d_r)\right]$$

• For efficient optimization, we adopt ADMM [1,2] and introduce auxiliary variables for data consistency and regularization terms:

$$1/2||k - \mathbf{M} \cdot \mathbf{E} \cdot m||_{2}^{2} + \lambda ||\mathbf{R} \cdot m||_{1}$$

$$c = \mathbf{E} \cdot m \qquad r = \mathbf{R} \cdot m$$

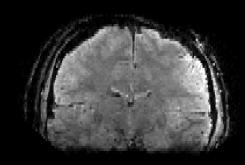
And the image update is found by a simple linear combination of data consistency and regularization: Preconditioned Conjugate Gradient for Total Variation

$$(\alpha \cdot S^{2} + \beta \cdot R^{2}) \cdot m = \alpha \cdot E^{H}(c - d_{c}) + \beta \cdot R^{H}(r - d_{r})$$

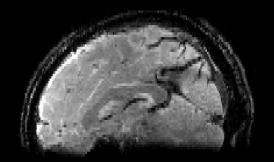
$$diag(R^{2}) = 6 \cdot I \text{ for TV since Laplacian}$$

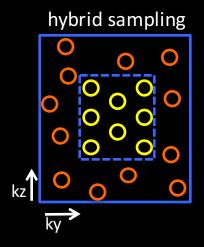
# Wave encoding with R=15 accl @ 7T

#### **Proposed: CS-Wave**





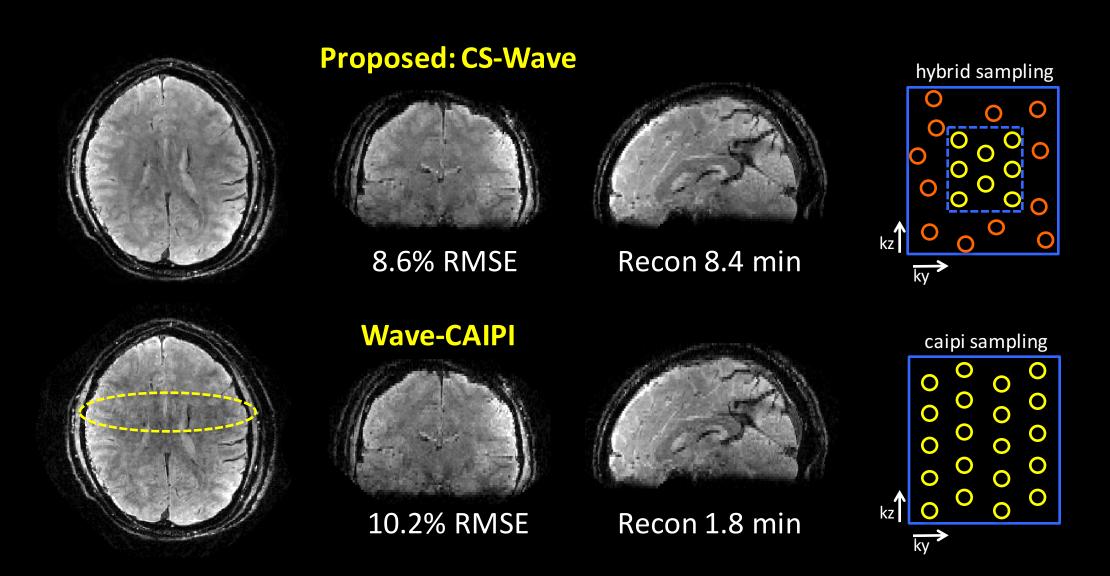




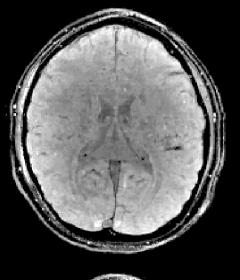
- Res =  $1x1x2 \text{ mm}^3$
- FOV = 224x222x120 mm<sup>3</sup> tight
- $^{-}$  TE/TR = 10.9/27 ms
- ESPIRiT [1] sensitivities from 16x16x16 points
- Hybrid sampling [2]: Center 25% w/ R=3x3 CaipiOuter 75% w/ VD Poisson

 $_{acq} = 25 \text{ sec}$ 

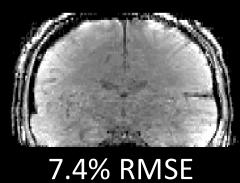
# Wave encoding with R=15 accl @ 7T

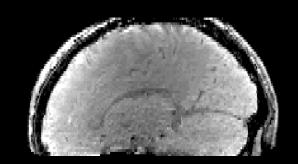


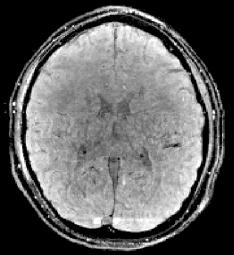
# Wave encoding with R=15 accl @ 3T



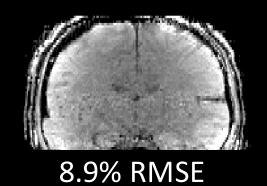


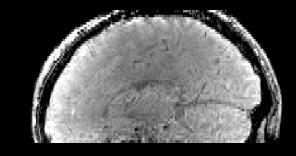






**Wave-CAIPI** 



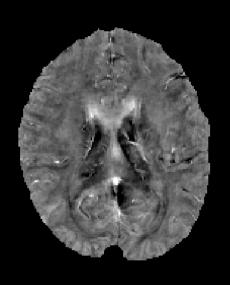


 $T_{acq} = 24 \text{ sec}$ 

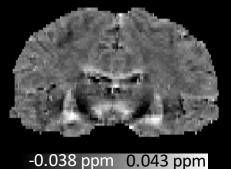
TE/TR = 13.3/26 ms

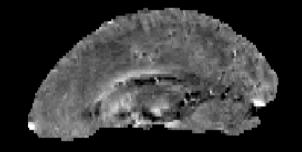
# Phase & QSM with R=15 accl @ 7T

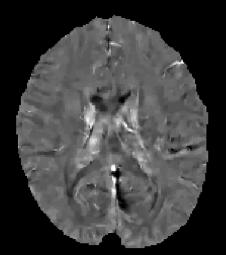
#### **Proposed: CS-Wave**



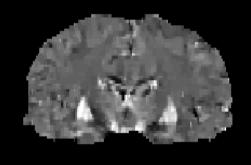






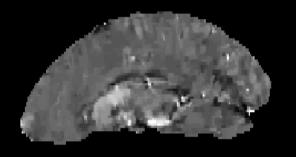


Susceptibility Map Single-Step TGV [3]



0.13 ppm

-0.09 ppm



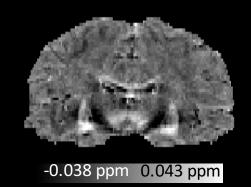
[3] I Chatnuntawech et al ISMRM'16, p.869 Thu 10:30 Sparse Road to Quantitative Imaging

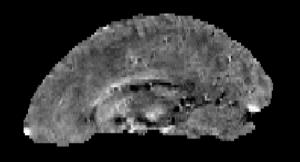
# Phase & QSM with R=15 accl @ 7T

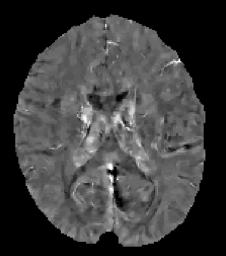
**Wave-CAIPI** 



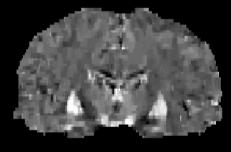




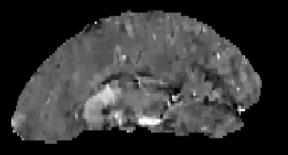




Susceptibility Map Single-Step TGV [3]



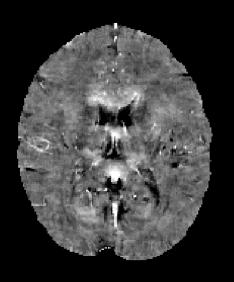




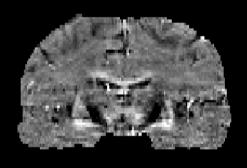
[3] I Chatnuntawech et al ISMRM'16, p.869 Thu 10:30 Sparse Road to Quantitative Imaging

# Phase & QSM with R=15 accl @ 3T

#### **Proposed: CS-Wave**



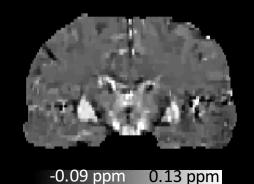
Tissue Phase

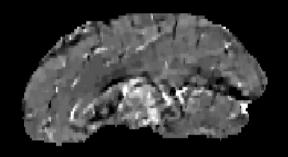


-0.038 ppm 0.043 ppm



Susceptibility Map Single-Step TGV [3]





[3] I Chatnuntawech et al ISMRM'16, p.869 Thu 10:30 Sparse Road to Quantitative Imaging

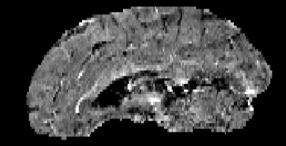
# Phase & QSM with R=15 accl @ 3T

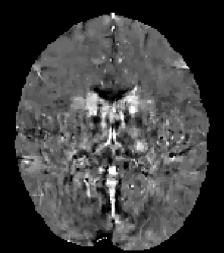
**Wave-CAIPI** 



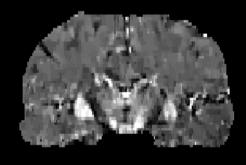


-0.038 ppm 0.043 ppm

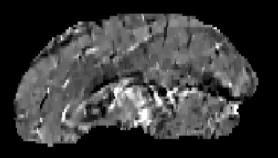




Susceptibility Map Single-Step TGV [3]



-0.09 ppm 0.13 ppm



[3] I Chatnuntawech et al ISMRM'16, p.869 Thu 10:30 Sparse Road to Quantitative Imaging

#### **Echo-Shift**

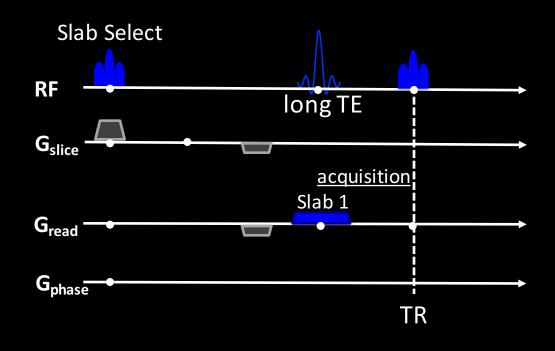
- For SWI and QSM, long TE is desired to build up phase and T<sub>2</sub>\* contrast, which leads to long TR and acquisition time
- Echo-shift exploits the unused sequence time and interleaves multiple echos within a single TR and improves efficiency in 2D [1] or 3D [2] acquisitions
- Echo-shift has also been used for fMRI (PRESTO) [3], and combined with (SMS) [4] for further acceleration for 2D imaging

<sup>[2]</sup> YJ Ma et al MRM'15

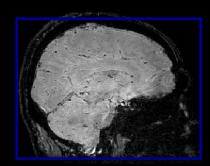
<sup>[3]</sup> G Liu et al MRM'93

# Multi-Slab Echo-Shift for 3D imaging

Conventional 3D-GRE: substantial unused time due to late TR

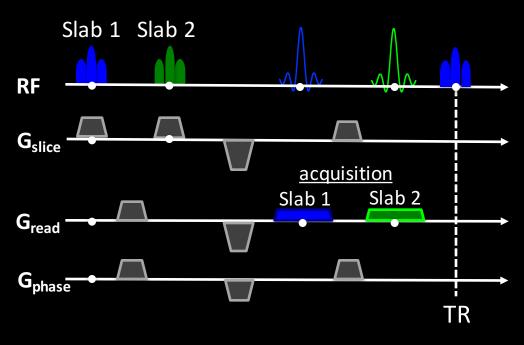


# Conventional 3D encoding

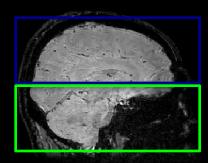


# Multi-Slab Echo-Shift for 3D imaging

Multi-Slab Echo-Shift: add a second readout and crusher gradients for faster encoding



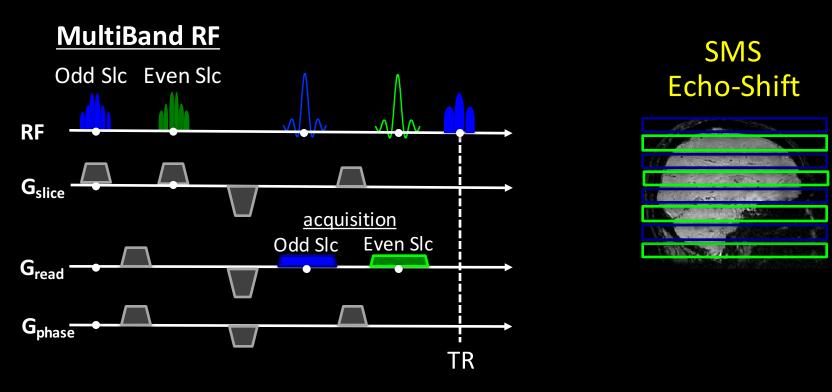
Multi-Slab Echo-Shift



- Slab boundary artifact
- Acceleration in head-foot more difficult since distance between aliasing voxels reduced by half

# SMS Echo-Shift for 3D imaging

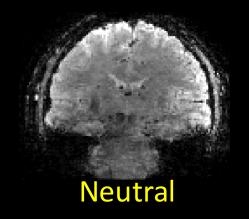
SMS Echo-Shift [1]: excite and encode comb slice groups



[1] H Ye et al ISMRM'16 p3246

# Echo-Shift CS-Wave with R=15×2 accl @ 3T

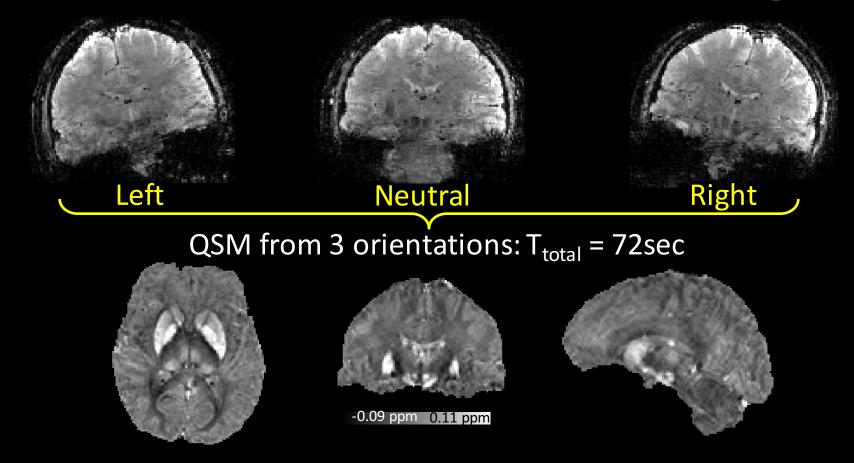






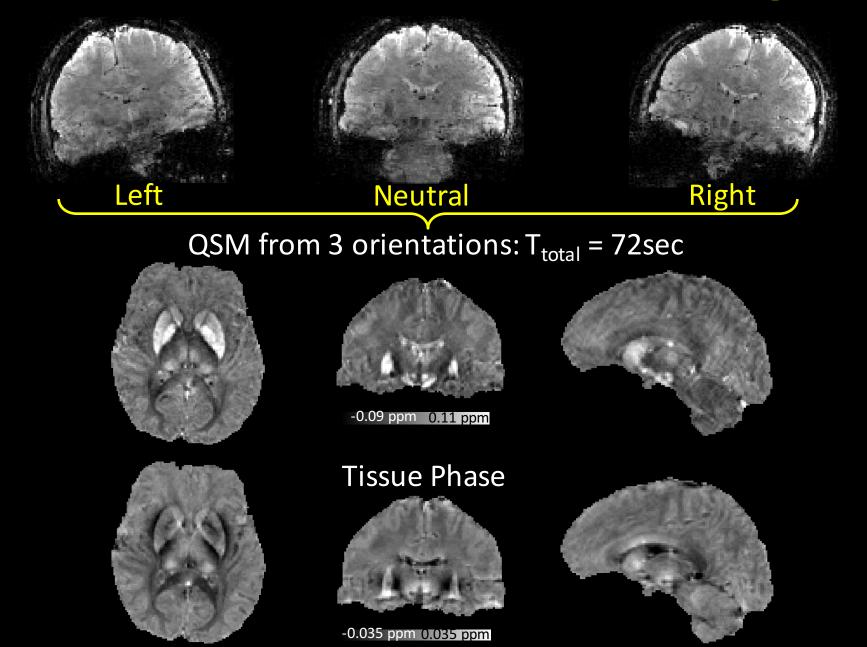
- **1.5** mm iso
- Long TE = 35 ms (TR = 47 ms)
- $T_{acq} = 24 sec$

# Echo-Shift CS-Wave with R=15×2 accl @ 3T



Combine information from 3 head orientations to solve QSM inverse problem [1]

# Echo-Shift CS-Wave with R=15×2 accl @ 3T



#### Conclusion

- We proposed optimized CS-Wave with efficient reconstruction and tailored datasampling
- SMS Echo-Shift strategy utilizes the unused sequence time for extra encoding
- Combining CS-Wave with SMS Echo-Shift permits 30-fold (15×2) acceleration
- This enables rapid SWI and QSM acquisition at long TE required for optimal contrast
- Questions / Comments:

berkin@nmr.mgh.harvard.edu

Support: NIH R24MH106096, R01EB020613, R01EB017337, U01HD087211